

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	7	deichmann and clausen near tais	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:29
S2	7	Deichmann near Nikolaj	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:31
S3	7	clausen near tais	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:31
S4	2990	calibrat\$3 near5 scanner\$3	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:32
S5	0	S4 and calibrat\$3 near object and calibrat\$3 near2 camera and tsai and activat\$3 near4 laser	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:33
S6	7	S4 and calibrat\$3 near object and calibrat\$3 near2 camera and tsai	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:33
S7	0	S4 and calibrat\$3 near object and activat\$3 and tsai	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:35
S8	4	S4 and calibrat\$3 near object and visible and tsai	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:35

S9	2	calibrat\$3 near object and calibrat \$3 near2 camera and tsai and activat \$3 near4 laser	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:36
S10	5	calibrat\$3 near object and calibrat \$3 near2 camera and tsai and laser near5 visible	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:38
S11	25	calibrat\$3 near object and calibrat \$3 near2 camera and tsai and laser and (orientat\$3 and position)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:40
S12	5	calibrat\$3 near object and calibrat \$3 near2 camera and tsai and laser with (orientat\$3 and position)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:40
S13	36	calibrat\$3 near object and calibrat \$3 near2 camera and tsai and (orientat\$3 and position)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:42
S14	40	calibrat\$3 near object and tsai and (orientat\$3 and position)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:46
S15	0	calibrat\$3 near object and tsai and (orientat\$3 and position) near6 (three near dimensional)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:48
S16	0	calibrat\$3 near object and tsai and (orientat\$3 and position) near6 (three- dimensional)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:48

S17	0	calibrat\$3 near object and (orientat \$3 and position) near6 (three- dimemsional)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:48
S18	728	calibrat\$3 near object and (orientat \$3 and position)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:49
S19	233	calibrat\$3 near object and (orientat \$3 and position) near5 object	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:49
S20	82	calibrat\$3 near object and (orientat \$3 and position) near5 (object and camera)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:49
S21	13	S20 and tsai	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:49
S22	5	(calibrat\$3 near object) near6 (two near plan\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:51
S23	59	(calibrat\$3 near object) near6 (three near dimensional)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:52
S24	40	S23 and angle\$3	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 14:52
S25	11	calibrat\$3 near object and angle\$3 near5 (two near plane)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 15:01

S26	11	calibrat\$3 near object and angle\$3 near5 (two near plane\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/12/03 15:01
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